

Content

This is an example of a MAPLE 7 worksheet for normalization, finding invariants and reduction of the following system:

$Dx = Mx + f_2(x) + f_3(x) + \text{higher order terms}$, where:

$$M := \begin{bmatrix} \alpha_1 & \alpha_2 & 0 \\ \alpha_3 & -\alpha_1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$f_2 := [\beta_1 x_1^2 + \beta_2 x_1 x_2 + \beta_3 x_2^2 + \mu_1 x_3 x_1 + \mu_2 x_2 x_3, \beta_4 x_1^2 + \beta_5 x_1 x_2 + \beta_6 x_2^2 + \mu_3 x_3 x_1 + \mu_4 x_2 x_3, 0]$$

$$f_3 := [\gamma_1 x_1^3 + \gamma_2 x_1^2 x_2 + \gamma_3 x_1 x_2^2 + \gamma_4 x_2^3 + \nu_1 x_1^2 x_3 + \nu_2 x_1 x_2 x_3 + \nu_3 x_2^2 x_3 + \rho_1 x_1 x_3^2 + \rho_2 x_2 x_3^2,$$

$$\gamma_5 x_1^3 + \gamma_6 x_1^2 x_2 + \gamma_7 x_1 x_2^2 + \gamma_8 x_2^3 + \nu_4 x_1^2 x_3 + \nu_5 x_1 x_2 x_3 + \nu_6 x_2^2 x_3 + \rho_3 x_1 x_3^2 + \rho_4 x_2 x_3^2, 0]$$

Disclaimer

While our testing, as well as computations of examples, indicate correctness and reliability of the programs, the authors cannot guarantee the correctness of any routine.

Program developed by S. Mayer (email: mayer@mathA.rwth-aachen.de)

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The programs may be used for any non-commercial purpose by individuals and scientific organizations.

Initialization

```
with(linalg):  
Warning, the protected names norm and trace have been redefined and  
unprotected
```

```
The Message: "Warning, the protected names norm and trace have been redefined and  
unprotected" will not inflict the following calculations. It derives from using the linalg package  
instead of the LinearAlgebra package, for the "linalg package is useful for doing computations  
in abstract linear algebra" (Maple glossary). This allows parameter dependent calculations.
```

Primitive operations

Procedures

Input

The vector field v is given in the form $v(x)=Mx+f_2[x]+...$ where M is an $n \times n$ matrix and the f_j are homogeneous polynomials $C^n \rightarrow C^n$ of degree j . The following routines are capable of working with parameters, so you might want to apply them for parameter dependent vector fields. Note that maple assumes non-degeneracies of all parameters.

```
Enter the linearization M of the vector field. The following calculations assume that M is  
semisimple.
```

```
> M:=matrix(3,3,[alpha[1],alpha[2],0,alpha[3],-alpha[1],0,0,0,0  
]);
```

$$M := \begin{bmatrix} \alpha_1 & \alpha_2 & 0 \\ \alpha_3 & -\alpha_1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Let targetspace be the desired degree of the normal form. targetspace then is also the degree of the Taylor expansion of the vector field.

```
> targetspace:=3;
```

```
targetspace := 3
```

Just evaluate the following lines.

```
> f:=vector(targetspace,0);
```

```
> dim:=rowdim(M);
```

```
dim := 3
```

```
> for i from 1 to targetspace do
```

```
>   f[i]:=vector(dim,0);
```

```
> od:
```

```
> f[1]:=Matrix2Polynom(M);
```

```
f1 := [α1 x1 + α2 x2, α3 x1 - α1 x2, 0]
```

Enter the higher order terms of the Taylor expansion of the vector field: f[2]:=vector(...);

```
f[3]:=... f[targetspace]:=vector(...);
```

```
> f[2]:=vector([beta[1]*x[1]^2+beta[2]*x[1]*x[2]+beta[3]*x[2]^2
+mu[1]*x[3]*x[1]+mu[2]*x[2]*x[3]
,beta[4]*x[1]^2+beta[5]*x[1]*x[2]+beta[6]*x[2]^2+mu[3]*x[3]*x
[1]+mu[4]*x[2]*x[3],0]);
```

```
f[3]:=vector([gamma[1]*x[1]^3+gamma[2]*x[1]^2*x[2]+gamma[3]*x
[1]*x[2]^2+gamma[4]*x[2]^3+nu[1]*x[1]^2*x[3]+nu[2]*x[1]*x[2]*
x[3]+nu[3]*x[2]^2*x[3]+rho[1]*x[1]*x[3]^2+rho[2]*x[2]*x[3]^2
,gamma[5]*x[1]^3+gamma[6]*x[1]^2*x[2]+gamma[7]*x[1]*x[2]^2+ga
mma[8]*x[2]^3+nu[4]*x[1]^2*x[3]+nu[5]*x[1]*x[2]*x[3]+nu[6]*x
[2]^2*x[3]+rho[3]*x[1]*x[3]^2+rho[4]*x[2]*x[3]^2,0]);
```

```
f2 :=
```

```
[β1 x12 + β2 x1 x2 + β3 x22 + μ1 x3 x1 + μ2 x2 x3, β4 x12 + β5 x1 x2 + β6 x22 + μ3 x3 x1 + μ4 x2 x3, 0]
```

```
f3 := [
```

```
γ1 x13 + γ2 x12 x2 + γ3 x1 x22 + γ4 x23 + ν1 x12 x3 + ν2 x1 x2 x3 + ν3 x22 x3 + ρ1 x1 x32 + ρ2 x2 x32,
```

```
γ5 x13 + γ6 x12 x2 + γ7 x1 x22 + γ8 x23 + ν4 x12 x3 + ν5 x1 x2 x3 + ν6 x22 x3 + ρ3 x1 x32 + ρ4 x2 x32, 0
```

```
]
```

Enter the maximal degree of calculated invariant polynomials.

```
> invariantsdegree:=2;
```

```
invariantsdegree := 2
```

Automatic initialization

```
> dim:=rowdim(M):
```

```
> minimalpoly:=minpoly(M,tau);
```

```
minimalpoly := (-α12 - α2 α3) τ + τ3
```

```
> sigmaset:=symmetriceigenvalues(minimalpoly,dim):
```

Determining annihilating polynomials

```
[ Annihilating polynomials for the action of ad M on P_r: (Remember that x -> p(-x) annihilates
the action of ad M on P_0 if p annihilates M.)
[ > liebracketannihilator:=AnnihilatingPolynomials(sigmaset,subs(
tau=-tau,minimalpoly),minimalpoly,dim,targetspace+1):
"Finished with step ", 1, "."
"Finished with step ", 2, "."
"Finished with step ", 3, "."
"Finished with step ", 4, "."
[ Now liebracketannihilator[j] annihilates the action of ad M on P_{j-1}.
[ > invpoly:=AnnihilatingPolynomials(sigmaset,minimalpoly,minimal
poly,dim,invariantsdegree):
"Finished with step ", 1, "."
"Finished with step ", 2, "."
[ Now invpoly[j] annihilates the action of L_M on S_j.
```

Output

```
> for j from 1 to targetspace+1 do
>   print("Annihilating polynomial for ad M on homogeneous
polynomials of degree",j-1);
>   print(liebracketannihilator[j]);
> od;
"Annihilating polynomial for ad M on homogeneous polynomials of degree", 0
      
$$\tau(-\tau^2 + \alpha_1^2 + \alpha_2 \alpha_3)$$

"Annihilating polynomial for ad M on homogeneous polynomials of degree", 1
      
$$(-4 \alpha_2 \alpha_3 + \tau^2 - 4 \alpha_1^2) \tau(\tau^2 - \alpha_1^2 - \alpha_2 \alpha_3)$$

"Annihilating polynomial for ad M on homogeneous polynomials of degree", 2
      
$$(-4 \alpha_2 \alpha_3 + \tau^2 - 4 \alpha_1^2) \tau(\tau^2 - \alpha_1^2 - \alpha_2 \alpha_3)(-9 \alpha_2 \alpha_3 - 9 \alpha_1^2 + \tau^2)$$

"Annihilating polynomial for ad M on homogeneous polynomials of degree", 3
      
$$(-16 \alpha_2 \alpha_3 + \tau^2 - 16 \alpha_1^2)(-4 \alpha_2 \alpha_3 + \tau^2 - 4 \alpha_1^2) \tau(\tau^2 - \alpha_1^2 - \alpha_2 \alpha_3)$$

      
$$(-9 \alpha_2 \alpha_3 - 9 \alpha_1^2 + \tau^2)$$

> print("Annihilating polynomial for L_M on homogeneous
polynomials of degree",0);print(1);
for j from 1 to invariantsdegree do
>   print("Annihilating polynomial for L_M on homogeneous
polynomials of degree",j);
>   print(invpoly[j]);
> od;
"Annihilating polynomial for L_M on homogeneous polynomials of degree", 0
      1
"Annihilating polynomial for L_M on homogeneous polynomials of degree", 1
      
$$\tau(-\tau^2 + \alpha_1^2 + \alpha_2 \alpha_3)$$

"Annihilating polynomial for L_M on homogeneous polynomials of degree", 2
      
$$(-4 \alpha_2 \alpha_3 + \tau^2 - 4 \alpha_1^2) \tau(\tau^2 - \alpha_1^2 - \alpha_2 \alpha_3)$$

```

Higher-order normalization

```

[ > dgl:=matrix(targetspace,targetspace): #the differential
  equation in the various transformed states
[ > Trafo:=vector(targetspace):Trafo[1]:=vector(dim,0): #the
  transformation is exp(Trafo).
[ > for i from 1 to targetspace do
  >   dgl[1,i]:=eval(f[i]);
[ > od:
[ > for i from 2 to targetspace do
  #print("starting with
  ",collect(expand(liebracketannihilator[i+1]),tau));
  >
  erg:=semisimplecalculation(M,collect(expand(liebracketannihil
  ator[i+1]),tau),f[i]);
  #print("transformation and transformed part in normal
  form calculated for one degree higher");
  >   for j from 1 to i-1 do
  >     dgl[i,j]:=eval(dgl[i-1,j]);
  >   od;
  #print("some terms are copied (degree < r)");
  >   Trafo[i]:=eval(erg[1]);
  >   dgl[i,i]:=eval(erg[2]);
  #print("some terms are chosen as it was calculated
  before");
  >   for j from i+1 to targetspace do
  >     dgl[i,j]:=eval(dgl[i-1,j]);
  >     k:=1;
  >     while j >= k*(i-1)+1 do
  >       hlp:=scalarmul(dgl[i-1,j-k*(i-1)],1/k!);
  >       for l from 1 to k do
  >         hlp:=lie(erg[1],hlp);
  >       od;
  >       dgl[i,j]:=matadd(dgl[i,j],hlp);
  >       k:=k+1;
  >     od;
  #print("transformation of higher terms up to degree
  ",j," done in this step")
  >   od;
  >   for j from i to targetspace do
  >     f[j]:=eval(dgl[i,j]);
  >   od;
  #print("transformation succesfull up to degree ",i);
[ > od:

```

The The previous lines compute Poincare-Dulac normal form up to degree targetspace. It is stored in the variable dgl. dgl is a field of dimension targetspace²:

dgl[i,1]+dgl[i,2]+...+dgl[i,targetspace] is the Poincare-Dulac-normal form up to degree i. The corresponding transformation is given by exp(ad(Trafo[i])) exp(ad(Trafo[i-1])) ... exp(ad(Trafo[2])). An output of the results is provided in the next steps:

+ *Output of the Poincare-Dulac normal form*

+ *Output of intermediate results*

– Invariants at fixed degree

```

[ > eval(invariantsdegree);

```

```
[ Choose a degree invdegree <= invariantsdegree;
> invdegree:=invariantsdegree;
                                invdegree := 2
```

– Invariant providing map

A map from the space of homogeneous polynomials of invdegree onto the invariant polynomials of invdegree is calculated.

```
[ > eval(invpoly);
                                [τ(-τ2 + α12 + α2 α3), (-4 α2 α3 + τ2 - 4 α12) τ (τ2 - α12 - α2 α3)]
```

Note that the command `InvariantsProvidingPolynomial(invpoly[deg],M)`; calculates the invariant providing map for degree deg, if deg<invariantsdegree.

```
[ > invpolymap:=InvariantsProvidingPolynomial(invpoly[invdegree],M);
```

$$\text{invpolymap} := 8 \alpha_1^2 \alpha_2 \alpha_3 + 4 \alpha_2^2 \alpha_3^2 + 4 \alpha_1^4 + \tau^2 (-5 \alpha_2 \alpha_3 - 5 \alpha_1^2) + \tau^4$$

– Finding the invariants

A basis of invariants of degree 'invariantsdegree' is calculated using 'invpolymap'. If you already know the dimension of the space of invariants from some theoretical argument, set 'number' to some positive value (in order to save calculation time) and thus only do 'number' tries for invariants. Another call of `invariants(...,eval(thistry),...)` will then try more invariants...

```
[ > Invarianten:={}: InvZahl:=0: firsttry:=vector(dim,0):
```

```
[ > firsttry[dim]:=invdegree:number:=-1:eval(firsttry);
                                [0, 0, 2]
```

```
[ > thistry, Invarianten, InvZahl:=invariants(invpolymap, eval(Invarianten), InvZahl, eval(firsttry), number, invdegree, dim, M);
```

```
thistry, Invarianten, InvZahl := [3, 0, 0], {2 α3 α12 α2 x22 + 2 α32 α22 x22 - 2 α2 α33 x12
- 2 α12 α32 x12 + 4 x2 α3 α13 x1 + 4 x2 α32 α2 α1 x1, 4 x32 (α22 α32 + 2 α12 α2 α3 + α14)},
2
```

If g is an invariant, and c a constant, c*g is also an invariant. So it is 'legal' to try to simplify further calculations by eliminating parameters.

```
[ > Inva:=vector(InvZahl):
```

```
[ > for i from 1 to InvZahl do
```

```
    Inva[i]:=factor(polynomialsimplify(Invarianten[i],dim));
od;
```

$$\text{Inva}_1 := -x_1^2 \alpha_3 + x_2^2 \alpha_2 + 2 x_2 \alpha_1 x_1$$

$$\text{Inva}_2 := x_3^2$$

– Reduced vector field

We are especially interested in the invariant independent of x[3], so set

```
[ > if depends(Inva[1],x[3]) then Inva:=Inva[2] else
    Inva:=Inva[1] fi;
```

$$\text{Inva} := -x_1^2 \alpha_3 + x_2^2 \alpha_2 + 2 x_2 \alpha_1 x_1$$

```
[ > Inva3a:=lieableitung(f[2],Inva):
```

```
[ > Inva3b:=lieableitung(f[3],Inva):
```

```
[ > theta[1]:=simplify(Inva3a/Inva/x[3]);
```

